

DRYWELLS DIMENSIONING: ANALOGY BETWEEN WATER FLOW IN SOIL AND HEAT FLUX IN MEDIA SOLIDS

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Abstract:

The drywell is an on-lot drainage system, which is composed by an excavation in the soil lined with a perforated piped and gravel at the bottom and sides. There are many models for on lot systems dimensioning, which were initially developed for agriculture areas or for simulation of water percolation in porous media, thus, they are not fully optimized for small areas like urban lots. This article proposes a model for dimensioning drywells, which is based on physical and hydrological characteristics of the installation site. It was developed using the analogy between water flow in soil and the heat flux in media solids. Results obtained with the proposed model were statistically similar ($p>0.05$) to those obtained with experimental data.

Keywords: On-lot drainage; drywell; analogy; infiltration.

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INTRODUCTION

The uncontrolled growth of impermeable areas in cities results in increase in surface runoff, which alters the runoff hydrograph with the increase in peak flow and the consequent floods. In this context, instead of conducting all the runoff generated by urban drainage systems outside the cities, there is a need to associate measures that deal with the management of rainwater in the place where runoff is generated.

On-lot drainage systems are auxiliary systems based on rainwater retention and detention techniques, including infiltration. As shown by Reis (2018), infiltration systems are hybrid systems that sometimes act as retention, when water is stored inside the system and then be infiltrated over time and, at others, as detention, when the system reaches its maximum volume capacity and starts to overflow, while a portion of water is infiltrated.

In general, in infiltration systems, rainwater is directed to a structure (or component) that is sized to store a certain volume of water while slowly infiltrating the soil.

The dry-well, which consists of an excavation in the ground, usually lined with a concrete tube drilled with gravel at the bottom and on the sides, protected by a layer of geotextile, is an example of an infiltration system.

The equation of the flow of water and air through the soil to represent the water content along the depth was proposed by Green and Ampt (1911), constituting the equations of the infiltration capacity in the soil.

Richards (1931) developed an equation with the total water potential that is equal to the sum of the capillary potential and the gravitational potential, which is used in the current equations to represent the flow of water in the soil. The Richards' equation is derived from the Darcy equation and determines the dynamics of water in an unsaturated soil in the vertical direction.

The Richards' equation is difficult to solve, considering the relationships among the variables involved in the process of water infiltration in the soil and the numerical solutions are very complex and require detailed soil data. As a result, several models were developed for an approximate analytical solution (Becker, 2016). Different approaches have been used in these models, which can be summarized in numerical and computational resolutions of the equations that expand the classic Richards's equation (Del Rio and López de Haro, 1991; El-Kadi and Ge, 1993).

A systematic mapping study (SMS) of articles in English published in journals indexed in three international databases (Web of Science; Scopus e Engineering Village-Compendex) with the expression ["water infiltration" AND model*] in 2017 resulted in 94 documents adhering to the research theme, including

backward searching, according to Levy and Ellis (2006): 40.4% of these articles use mathematical modeling; 25.5% use modeling by physical theories and 34.0% use partial differential equations solving (Figure 1).

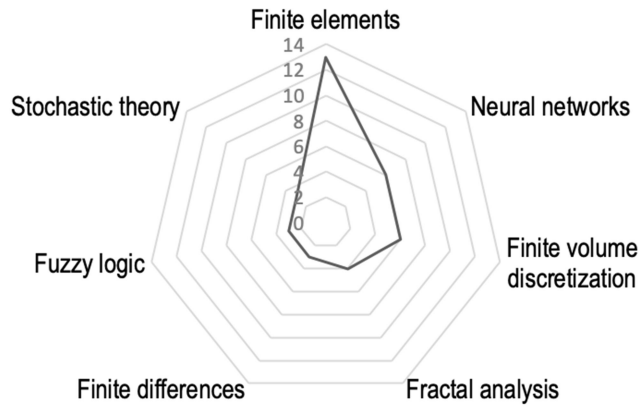
Twenty-five percent of the 38 articles that show mathematical modeling employ the techniques of: Finite elements (Arampatzis et al., 2001; Baca et al., 1997; Bause and Knabner, 2004; Bergamaschi and Putti, 1999; Duchene et al., 1994; Farhinet al., 2003; Hou and Wu, 1997; Ju and Kung, 1997; Lee et al., 2004; Norambuena-Contreras et al., 2012; Solin and Kuraz, 2011; Tan et al., 2004; Wu, 2010); Neural networks (Chua and Wong, 2010; Dorofki et al., 2014; Jain and Kumar, 2006; Goldshleger et al., 2012; Nestorl, 2006; Parchami-Aragui et al., 2013) and Finite volume discretization (Aravena and Dussailant, 2009; Calvo and Lisbona, 2001; Huber and Helmig, 2000; Lunati and Jenny, 2006; Manzini and Ferraris, 2004); Twarakavi et al., 2008).

The technique of finger phase field by gravity is used by 22% of the 23 articles that shows modeling by physical theories (Cueto-Felgueroso and Juanes, 2009a; 2009b; Eliassi and Glass, 2003; Furst et al., 2009; Glass and Yarrington, 2003) and 40% of the 32 articles that show models based on partial differential equations solving employ the techniques of: Laplace transforms (Fytius and Smith, 2001; Ginting, 2012; Jenkins et al., 2001; Nikzad et al., 2016; Srivastava and Yeh, 1991; Wu et al., 2012; Zaradny, 2008; and Pedotransfer functions (Baker and Ellison, 2008; Dashtaki et al., 2010; Dhikary et al., 2008; Haghverdi et al., 2012; Schaap and Leji, 1998; Tomasella et al., 2003).

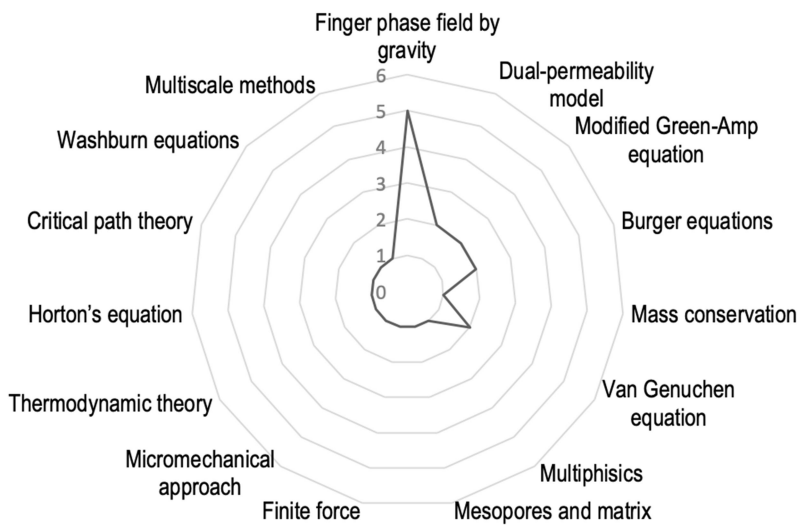
However, as shown by Li and Babcock Jr (2014), most models for assessing the performance of infiltration systems are not fully optimized for the specific characteristics of on-lot drainage systems, since their initial development was made for agriculture or the simulation of water percolation in porous media.

In addition, according to Graham et al (2014), the current modeling software were developed for the determination of peak flows and dimensioning of transport systems and are, for the most part, unsuitable for spatially distributed control systems, as is the case of on-lot drainage systems.

According to Reis (2018), models currently used hardly represent with the expected performance the hydrological processes resulting from low impact development strategies. This author also emphasizes that this statement is shared by different researches, such as: Krebs et al. (2016); Zhang and Guo (2014); Li and Babcock Jr. (2014); Burszta-Adamiak and Mrowiec (2013); Lee et al. (2013); Christianson et al. (2012); Furumai et al. (2005); and Graham et al. (2004).



Modeling by physical theories



Modeling based on partial differential equations solving

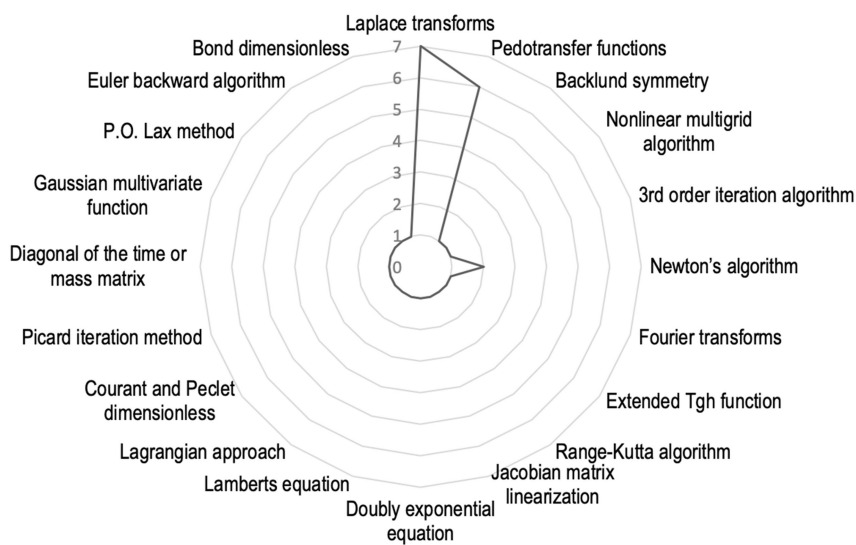


Fig. 1: Results of the SMS – 98 articles published in English.

In this context, the present work presents an alternative model for the dimensioning of drywells, which starts from a unidirectional water flow and incorporates interface coefficients to represent the three-dimensional behavior of the water flow in the soil. The proposed formulation is based in the theory of the Domain Transfer via Analogy – TDA (Klenk and Forbus; 2009). TDA uses the knowledge of a base (or source) domain, which already has its equation consolidated, to explain a problem or issue to be resolved - the target domain. A domain can be composed of a system of objects or entities; attributes (description of objects) or relationships between objects (GENTNER, 1983).

MATERIALS AND METHOD

TDA is usually composed of 4 stages (Klenk and Forbus, 2009): definition of the base domain; definition of the target domain, development of correspondences between the two domains and application. In the present study, the target domain is composed of the relationships between the determinants of the water flow in the soil, more specifically, those involved in determining the filling time of drywells.

The filling time of an on-lot drainage system is defined as the period between the moment the first raindrop reaches the system until the moment when it overflows, when the water is directed to the urban drainage system. For the proper determination of the filling time of a dry-well, it is important to know the interaction between the soil layers, since it has a heterogeneous composition.

The interaction between different materials is already well resolved when considering the phenomenon of heat transfer in solid media (Aseka, 2003; Mendes, 1997; Upadhyay et al., 1975). Thus, the relationships between the variables that determine the heat flux in solid media were selected as the base domain.

The Laplace equation, which is used to determine the heat flux in solid media, combines the Fourier equation and the general thermal conduction equation. For the flux in a single direction (x) in a transient regime, with the temperature varying in time and without generating internal heat, the general equation of thermal conduction is expressed in **Eq. 1** (Kreith and Bohn, 2003):

$$T_{i+1}^m = T_i^m + \alpha \Delta t \left[\frac{(T_{i+1}^m + T_{i-1}^m + 2T_i^m)}{\Delta x} \right] \tag{1}$$

with **(Eq.2)**:

$$\alpha = \frac{k}{\rho c} \tag{2}$$

or **(Eq.3)**:

$$T_{i+1}^m = T_i^m + \frac{k \Delta t}{\rho c} \left[\frac{(T_{i+1}^m + T_{i-1}^m + 2T_i^m)}{\Delta x^2} \right] \tag{3}$$

where: T_{i+1}^m Temperature of the layer i+1 at time m [°C]
 T_i^m Temperature of the layer i at time m [°C]
 T_{i-1}^m Temperature of the layer i-1 at time m [°C]
 k Thermal conductivity [kcal/h.m.K]
 ρ Specific mass [kg/m³]
 c Specific heat [kcal/kg.K]
 Δt Time increment [s]

Similarly, the Richards equation is used in the target domain to determine the water flow in the vertical direction in the unsaturated soil. Richards equation combines Darcy and continuity equations. For saturated soils, with flow in a single direction (x) and transient regime, where moisture varies over time, and without generating internal flow, **Eq. 4** can be used:

$$h_{i+1}^m = h_i^m + \alpha \Delta t \left[\frac{(h_{i+1}^m + h_{i-1}^m + 2h_i^m)}{\Delta x^2} + \frac{q}{k} \right] \tag{4}$$

or **(Eq.5)**:

$$h_{i+1}^m = h_i^m + \frac{k \Delta t}{\rho c} \left[\frac{(h_{i+1}^m + h_{i-1}^m + 2h_i^m)}{\Delta x^2} \right] \tag{5}$$

with **(Eq.6)**:

$$\alpha = \frac{k}{\rho c} \tag{6}$$

where:

h_{i+1}^m Moisture of layer i+1 at time m [%]
 h_i^m Moisture of layer i at time m [%]
 h_{i-1}^m Moisture of layer i-1 at time m [%]
 Δt Time increment [s]
 q Affluent flow in the system [m³/s]
 k Hydraulic conductivity [m/s]
 ρ Specific mass [kg/m³]
 c Porosity [%]

Eq. 6 can also be expressed in terms of the only time-varying parameter, which is moisture, resulting in **Eq. 7**:

$$h_{i+1}^m = h_i^m + \alpha \Delta t \left[\frac{(h_{i+1}^m + h_{i-1}^m + 2h_i^m)}{\Delta x^2} + \frac{q}{k} \right] \tag{7}$$

The heat flux causes the variation in the internal energy of a solid. Similarly, the flow of water from the infiltration system causes variation in the moisture of the underlying layers. **Fig. 2** illustrates this analogy: on the left side, the heat flux from material i-1 to material i+1 causes an increase of the temperature of material i in the time interval Δt (the temperature T_i^{m+1} is higher than the temperature T_i^m); similarly, on the right side, the flow of water from layer i-1 to layer i+1 causes an increase in the moisture of the layer I in the interval Δt (the moisture h_i^{m+1} is higher than the moisture h_i^m).

Thus, similarly, the moisture of layer *i* at time *m*+1 can be determined by **Eq. 8**:

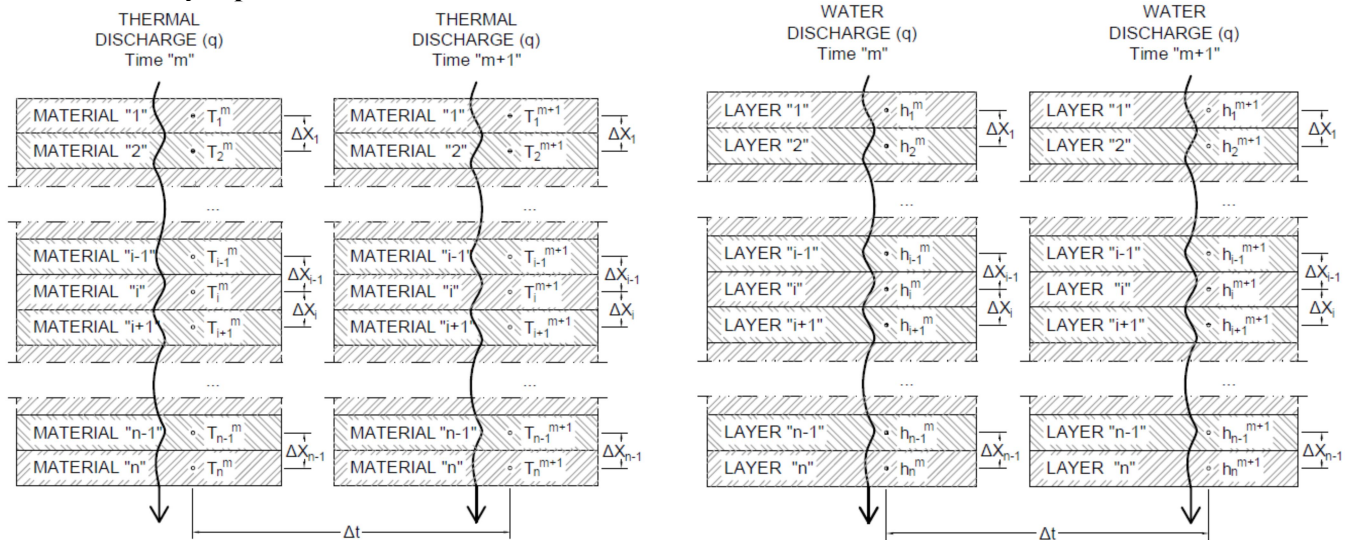


Fig. 2: Analogy between the temperature variation caused by the heat flux (thermal discharge) through the layers of a solid and the moisture variation caused by the water flow through the soil layers.

$$h_i^{m+1} = h_i^m + \frac{k_i \Delta t}{\Delta X^2 \eta_{s,i}} (h_{i+1}^m - 2 h_i^m + h_{i-1}^m) \quad (8)$$

where

h_i^{m+1} Moisture of soil layer *i* at time *m*+1 [%]

h_i^m Moisture of soil layer *i* at time *m* [%]

k_i Hydraulic conductivity of the soil layer *m* [m/s]

Δt Time increment [s]

ΔX Soil layer thickness [m]

$\eta_{s,i}$ Porosity of the soil layer *i* [%]

h_{i+1}^m Moisture of soil layer *i*+1 at time *m* [%]

h_{i-1}^m Moisture of soil layer *i*-1 at time *m* [%]

Data collected in an experimental installation composed of two drywells (**Fig. 3**), each with an internal diameter of 1.10m, total depth of 1.50m and effective depth of 0,87 were used for the validation of the proposed model. The drywells were made with perforated concrete pipes and a gravel layer at the bottom with a thickness of 0,50m. The drywells were dimensioned for a design flow rate of 6.54 m³.h⁻¹, which is equivalent to a rain with a return period of 2 years and duration of 10min, determined by the equation proposed by Zuffo and Leme (2005).

The conductivity of the soil in the experimental area was determined by Reis (2018) and it is equal to 1.382 * 10⁻⁵ m.s⁻¹ and porosity is 40.84%. The water level in each layer was determined at 10-second intervals using level sensors installed inside the experimental drywells.

Thirty-one design flow rates were simulated, resulting in 4.303 water level values as a function of time.

According to Reis and Ilha (2014), before each test, the dry-well were filled and emptied three time in a row, in order to increase the moisture of the soil in the contour region, creating a more unfavorable operation condition. Thus, only the data collect after the fourth filling procedure were considered in the analyses.

RESULTS AND DISCUSSION

Four layers were considered for the model formulation (**Fig. 4**):

- a) Gravel layer at the bottom of the dry-well;
- b) First layer of soil below the gravel layer;
- c) *i*-th layer of soil; and
- d) *n*-th layer of soil.



Fig. 4 Experimental dry-well. Source: Ferreira, Reis and Ilha (2016)

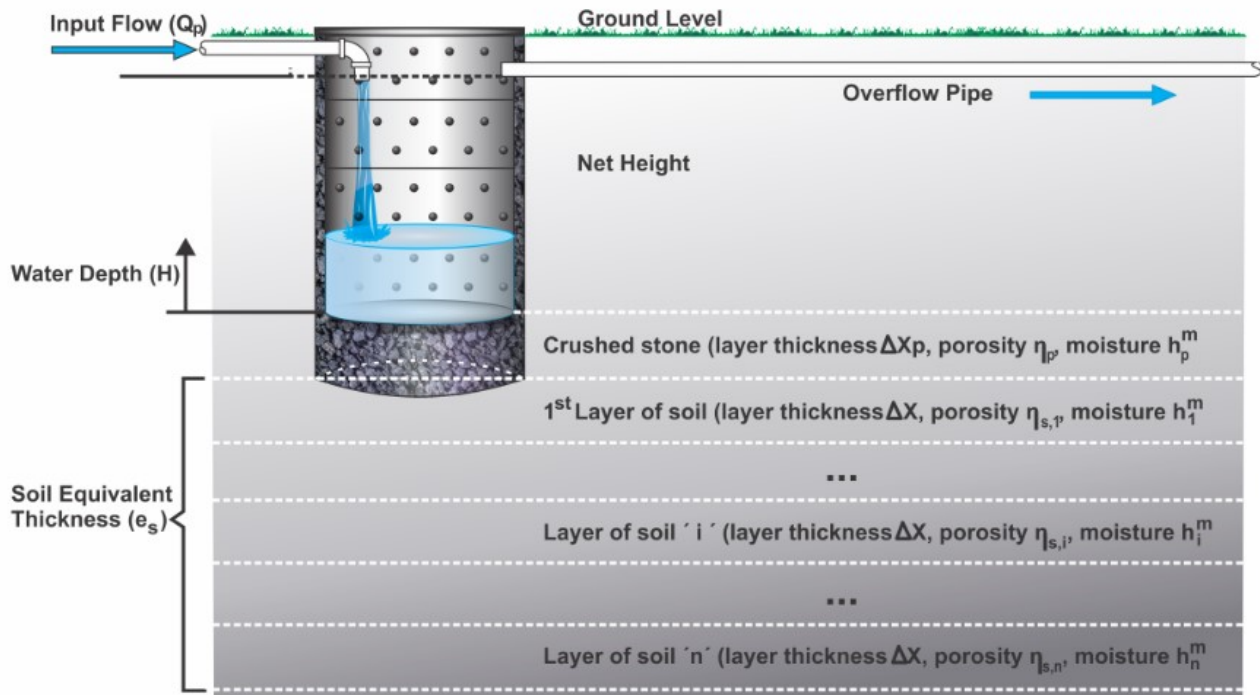


Fig. 4 Scheme of the on-lot drainage system (dry-well + soil) used for the formulation of the model.

The gravel layer receives the contribution of the rain and its moisture varies over time according to Eq. 9:

$$h_p^{m+1} = h_p^m + \frac{[2k_{s,1}A_p(h_1^m - h_p^m)] + Q_p}{\Delta X} \left(\frac{\Delta t}{A_p \eta_p \Delta X_p} \right) \quad (9)$$

Where:

- h_p^{m+1} Moisture of the gravel layer p at time m+1 [%]
- h_p^m Moisture of the gravel layer p at time m [%]
- h_1^m Moisture of the first layer of soil below the gravel layer at time m [%]
- $k_{s,1}$ Hydraulic conductivity of the first layer of soil [m/s]
- A_p Gravel area in the dry-well [m²]
- ΔX_p Gravel layer thickness [m]
- ΔX Layer thickness [m]
- Q_p Design flow rate [m³.h⁻¹]
- Δt Time interval used for each iteration [s]

The soil layer below the gravel layer receives the contribution of the upper layer and the moisture varies over time according to Eq. 10:

$$h_1^{m+1} = h_1^m + \frac{2h_b^m - 3h_1^m + h_2^m}{\Delta X} \left(\frac{k_{s,1} \Delta t}{\Delta X \eta_{s,1}} \right) \quad (10)$$

Where:

- h_1^{m+1} Moisture of the first layer of soil below the gravel layer at time m+1 [%]
- h_1^m Moisture of the first layer of soil below the gravel layer at time m [%]
- h_2^m Moisture of the second layer of soil below the gravel layer at time m [%]
- $k_{s,1}$ Hydraulic conductivity of the first layer of soil [m/s]

- ΔX Layer thickness [m]
- Δt Time interval used for each iteration [s]
- $\eta_{s,1}$ Porosity of the first layer of soil [%]

Similarly, Eq. 11 can be used to determinate the temporal variation in moisture of a generic layer i and Eq. 12 for the n-th layers of soil below the gravel layer at the bottom of the dry-well:

$$h_i^{m+1} = h_i^m + \frac{(h_{i+1}^m - 2h_i^m + h_{i-1}^m)}{\Delta X} \left(\frac{k_{s,i} \Delta t}{\Delta X \eta_{s,i}} \right) \quad (11)$$

$$h_n^{m+1} = h_n^m + \frac{(h_n^m - h_{n-1}^m)}{\Delta X} \left(\frac{k_{s,n} \Delta t}{\Delta X \eta_{s,n}} \right) \quad (12)$$

Where:

- h_i^{m+1} Moisture of the soil layer i at time m+1 [%]
- h_i^m Moisture of the soil layer i at time m [%]
- h_n^{m+1} Moisture of the soil layer n at time m+1 [%]
- h_n^m Moisture of the soil layer n at time m [%]
- $k_{s,i}$ Hydraulic conductivity of the soil layer i [m/s]
- $k_{s,n}$ Hydraulic conductivity of the soil layer n [m/s]
- ΔX Layer thickness [m]
- Δt Time interval used for each iteration [s]
- $\eta_{s,i}$ Porosity of the soil layer i [%]
- $\eta_{s,n}$ Porosity of the soil layer n [%]

These equations refer to the process of filling the dry-well, when the moisture at the time m+1 is higher than the moisture at the time m. The values of hydraulic conductivity were generically called K_s in the proposed model.

Considering the moisture values of a given layer at the initial instant, the water level is obtained iteratively at that instant. From this, the minimum thickness of the

soil layer, that is, the smallest relationship between hydraulic conductivity and drainable porosity is selected.

For the determination of the drainable porosity of the gravel layer, NM53 (ABNT, 2009) was used. Drainable porosity is the volume of soil pores in which water moves freely (Queiroz, 1997) and is similar to internal energy when considering the heat flux in solid media in the base domain.

Determining the drainable porosity in the field is complex, time consuming and expensive. Thus, it was considered an empirical equation for its determination.

Considering the compilation of equations presented by Ribeiro et al. (2007) and using the hydraulic conductivity of the soil of the experimental installation used for the validation of the proposed model, which will be described in the following ($k = 1.382 * 10^{-5}$ m/s), the Chossat and Sagnac equation was selected (standard error of the estimate equals to 77.48 and correlation coefficient of 0.97, when compared with experimental data), expressed in Eq. 13:

$$\eta = 0,025 + 0,0006k^{0,5} \tag{13}$$

where k – hydraulic conductivity [m/dia]

The depth of the soil, represented by the number of layers, can then be determined. Again, considering the base domain, the thermal thickness is similar to the equivalent soil thickness.

The thermal thickness is equivalent to the thickness of a material that conducts the same amount of heat over the same period of time as another element with different thickness and can be calculated by Eq. 14:

$$Q = \frac{Ak_x\Delta T}{e_x} = \frac{Ak_y\Delta T}{e_y} \tag{14}$$

where:

- Q Design flow rate [m³/h]
- A area [m²]
- k_x Thermal conductivity of the material x [kcal/s.m.°C]
- k_y Thermal conductivity of the material y [kcal/s.m.°C]
- ΔT Temperature difference at the layer under analysis [°C]
- e_x Thickness of the layer x [m]
- e_y Thickness of the layer y [m]

Thus, to determine the depth of soil to be considered in the model, the water flow in the gravel layer was considered equal to the equivalent soil thickness, with the same surface area an at the same time. For this, Eq. 15 can be used:

$$Q = \frac{A_b\eta_b\Delta X_b}{\Delta t} = \frac{A_b\eta_s e_s}{\Delta t} \tag{15}$$

where:

- e_s Equivalent soil thickness [m]
- η_b Porosity of the gravel layer [%]
- ΔX_b Gravel layer thickness [m]
- η_s Drainable porosity of the soil [dimensionless]

The minimum thickness resulting of each layer of soil below the gravel layer in the experimental drywell is 0.09m. Thus, the equivalent thickness (e_s) is 6.60m, that is, 73 soil layers to be analyzed in the model. The iteration process was considered complete when the water level reached the effective depth of the experimental drywell, that was defined as a function of its filling time.

To define the interface coefficients, TDA was also used and the base domain is composed by the thermal resistances. According to Kreith and Bohn (2003), when two surfaces with different conductivity are in contact, a resistance develops at the interface between them. Similarly, in the water flow in the soil, the hydraulic resistance (interface coefficient) can be also expressed in terms of the relationship between hydraulic conductivity and the cross area to the water flow.

Four interface coefficients were defined, which were incorporated into Eq. 9 to Eq.12:

- C_{ar,b} - interaction between water and gravel;
- k₁ - hydraulic conductivity around the dry-well;
- k₂ - hydraulic conductivity along the soil depth;
- C_{b,s} - interaction between gravel and soil; and
- k₃ - interaction of the holes in the side walls and the soil around the dry-well.

The interface coefficients were obtained by minimizing errors between the experimentally measured values and the filling times of the drywell.

The formulation of the equations for determining the interface coefficients was made using Buckingham’s Theorem PI, which can be expressed by Eq. 17 (Fox et al., 2014):

$$G(\pi_1, \pi_2, \pi_3, \dots \pi_n) = 0 \tag{17}$$

where $\pi_1, \pi_2, \pi_3, \dots \pi_n$ are independent parameters, which are obtained through the combination of predefined variables. From different types of equations, the one with the highest correlation coefficient with the measured data was selected.

The analogies were considered for the definition of the independent parameters are: design flow rate and heat flux; and cross-sectional area for water flow and cross-sectional area for heat flux. Thus, the equation for the gravel layer filling time was determined, based on the experimental design flow rates used for the determination of the interface coefficients, with the potential adjustment.

The resulting expressions are shown in Eq. 18 to Eq. 21.

$$h_b^{m+1} = C_{ar,b} \left\{ h_b^m + \left[\frac{2k_1 k_2 k_{s,1} (h_1^m - h_b^m) + Q_p}{\Delta X} \right] \frac{\Delta t}{(\eta_b \Delta X_b)} \right\} \quad (18)$$

$$h_1^{m+1} = C_{b,s} \left\{ h_1^m + \left[\frac{2h_b^m - 3h_1^m + h_2^m}{\Delta X} \right] \frac{k_1 k_2 k_{s,1} \Delta t}{(\eta_{s,1} \Delta X)} \right\} \quad (19)$$

$$h_i^{m+1} = C_{i,i+1} \left\{ h_i^m + \left[\frac{h_{i+1}^m - 2h_i^m + h_{i-1}^m}{\Delta X} \right] \frac{k_1 k_2 k_{s,i} \Delta t}{(\eta_{s,i} \Delta X)} \right\} \quad (20)$$

$$h_n^{m+1} = h_{n-1}^m + \left(\frac{h_{n-1}^m - h_n^m}{\Delta X} \right) \frac{k_1 k_2 k_{s,n} \Delta t}{(\eta_{s,n} \Delta X)} \quad (21)$$

Results obtained with the proposed model were not significantly different from the data measured experimentally for the significance level of 5%. The sum of residues (Fig. 5) resulted in 0.04 and the sample was equal to 1.12, which meets the criteria established in Bussab and Morettin (2002). With the filling time, the effective depth of the drywell can be estimate using the Least Squares Method, based on (Eq. 22):

$$H_D = \frac{Q_p(T_{O,G-0} + T_{O,G})}{S_p} \quad (22)$$

where:

- H_D = effective depth of the drywell [m];
- Q_p = design flow rate [m^3/h];
- $T_{O,G-0}$ = filling time of the drywell [s];
- S_p = permeable surface composed of the gravel layer at the bottom of the drywell and the side holes [m^2].
- $T_{O,G}$ = filling time of the gravel layer [s];

Thus, the equation for determining the effective depth of the drywell resulted in Eq. 23, with $R^2 = 0,999$:

$$H_D = 1,094Q_p^{-0,136} \quad (23)$$

Considering the design flow rate of $6.54 m^3 \cdot h^{-1}$, which was used for the design of the experimental drywells, the effective depth is 0.85m. This value is approximately equal to the experimental depth (0,87), which indicates the adherence of the proposed model.

CONCLUSIONS

The use of domain transfer via analogy enabled the development of a one-dimensional space-time model along the axis of the drywell that incorporates interface coefficients to simulate the three-dimensional water flow that occurs in water infiltration in the soil.

The modeled water level did not differ significantly ($p>0.5$) from the data observed experimentally, which indicates the adequacy of the proposed model. The filling time determination according to the physical and hydrological characteristics of the place where the drywell will be installed consists of an advance in relation to the methodologies usually used for this purpose. The proposed model can be used in soils with similar hydraulic conductivities, surface drained by the

drywell and gravel porosity, which demonstrates its versatility for different design situations.

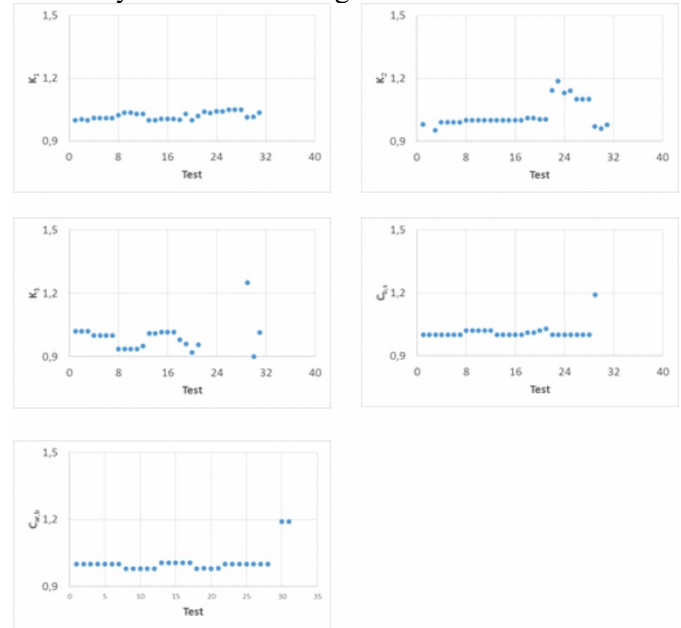


Fig. 5 Interface coefficients as a function of experimental design flow rates.

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